TensorFlow

Tom Rochette <tom.rochette@coreteks.org>

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0.1 Context

TensorFlow has rapidly grown in popularity due to the fact that is developed/supported by Google. As more and more developers move to the platform, it becomes essential to learn how it works and have a general idea of the various concepts it makes use of. This is a short article about some of these concepts.

0.2 Learned in this study

0.3 Things to explore

1 Overview

- Computations are represented as graphs
- Graphs are executed in the context of Sessions

2 Building a graph

• Start with ops that do not need any input (called source ops), such as Constant

3 Session

- Graphs are executed within a session (context) session = tf.session()
- Sessions are given one or many tensor to resolve session.run([tensorA, tensorB])
- Once we're done with a session, it should be closed session.close()

4 Tensors

A tensor is simply a multidimensional array of data. A scalar is a 0-D tensor, a vector is a 1-D tensor, a matrix is a 2-D tensor and anything over 3-D is called an n-D tensor.

Rank: The number of dimensions of a tensor.

Rank	Math entity	Example
0	Scalar	s = 483
1	Vector	v = [1.1, 2.2, 3.3]
2	Matrix	m = [[1, 2, 3], [4, 5, 6], [7, 8, 9]]
3	3-Tensor	t = [[[2], [4], [6]], [[8], [10], [12]], [[14], [16], [18]]]

Shape: A vector describing the number of elements at each point within a dimension.

Rank	Shape	Dimension number	Example
0	[]	0-D	A 0-D tensor. A
			scalar.
1	[D0]	1-D	A 1-D tensor with
			shape $[5] = [1, 2, 3, 4,$
			5].
2	[D0, D1]	2-D	A 2-D tensor with
			shape $[3, 4] = [[1, 2,$
			3, 4], [1, 2, 3, 4], [1, 2,
			3, 4]].
3	[D0, D1, D2]	3-D	A 3-D tensor with
			shape $[1, 4, 3] = [[[1, 4, 3]]]$
			2, 3], [1, 2, 3], [1, 2,
			3], [1, 2, 3]]].
\mathbf{n}	$[D0, D1, \ldots,$	n-D	A tensor with shape
	Dn]		$[D0, D1, \dots Dn].$

Type: Type of the data contained within the tensor.

Data type	Description
DT_FLOAT	32 bits floating point.
DT_DOUBLE	64 bits floating point.
DT_INT64	64 bits signed integer.
DT_INT32	32 bits signed integer.
DT_INT16	16 bits signed integer.
DT_INT8	8 bits signed integer.
DT_UINT8	8 bits unsigned integer.
DT_STRING	Variable length byte arrays. Each element of a Tensor
	is a byte array.
DT_BOOL	Boolean.
DT_COMPLEX64	Complex number made of two 32 bits floating points:
	real and imaginary parts.
DT_QINT32	32 bits signed integer used in quantized Ops.
DT_QINT8	8 bits signed integer used in quantized Ops.
DT_QUINT8	8 bits unsigned integer used in quantized Ops.

5 Variables

- Variables must be initialized (tf.initialize_all_variables())
- Initialization is an operation, and thus must be executed within a session

6 Fetches

• All the ops needed to produce the values of requested tensors are run once (not once per requested tensor)

7 Feeds

- Temporarily replaces the output of an operation with a tensor value (act as a placeholder)
- The feed data is provided as an argument to a session.run() call sess.run([output], feed_dict={input1:[7.], input2:[2.]})

8 Operations/Functions of interest

8.1 CNN

- tf.nn.conv2d(input, kernel, strides, padding): apply a convolution using kernel
- tf.nn.relu(input): rectifier linear unit, every negative value is set to 0, and positive values are kept the same
- tf.sigmoid(input): returns a value in the range [0.0, 1.0]
- tf.tanh(input): returns a value in the range [-1.0, 1.0]
- tf.nn.dropout(input, keep_prob): set the output to 0.0 based on a given probability. The output is multiplied by 1/keep_prob in order to keep the expected sum unchanged
- tf.nn.max_pool(input, kernel, strides, padding): take the maximum value found within a certain kernel size
- tf.nn.avg_pool(input, kernel, strides, padding): averages out all the values at each depth found within a kernel size
- \bullet tf.nn.local_response_normalization

8.2 RNN

- tf.nn.rnn_cell.BasicRNNCell(num_neurons): declares a recurrent neural network cell
- tf.nn.dynamic_rnn(network, input): simulate the given RNN
- tf.nn.rnn_cell.LSTMCell(num_neurons): declares a long short-term memory neural network cell
- tf.nn.rnn_cell.GRUCell(num_neurons): declares a gated recurrent unit cell

9 CNN

- Used mostly to process high density matrices where the data surrounding a value is generally highly
 correlated with it
- Apply the convolution operator to a 2d matrix using a given kernel/filter

10 RNN

• Used to process sequential inputs (speech recognition, speech synthesis, connected handwriting recognition, time-series forecast, image caption generation, end-to-end translation)

11 See also

12 References

- https://www.tensorflow.org/
- https://medium.com/jim-fleming/loading-tensorflow-graphs-via-host-languages-be10fd81876f